## Case study validation of HWRF-HYCOM and HWRF-POM for Hurricane Isaac (2012)

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- Review of 2014 version of HWRF-HYCOM and HWRF-POM
- Time series comparisons of both models versus surface ocean observations
- Scatterplots of water temperature profiles
- Conclusions

HWRF-HYCOM documented in:

Kim, H.-S., , C. Lozano, V. Tallapragada, D. Iredell, D. Sheinin, H. L. Tolman, V. M. Gerald, and J. Sims, 2014: Performance of ocean simulations in the coupled HWRF–HYCOM model. *J. Atmos. Oceanic Technol.*, **31**, 545–559.

### 3D ocean:



#### HYCOM:

...

- a. dx/dy=9km on Mercator
- b. 32 hybrid layers
- c. Relatively finer resolution of MLD 1 m (top), 4 m (2<sup>nd</sup>),

#### d. KPP mixing

#### <u>POM:</u>

- a. dx/dy=9km
- b. 24 levels
- c. Coarse resolution of MLD
  - 10 m (top), 20 m (2<sup>nd</sup>), ...
- d. M-Y mixing

## eddy-resolving vs. eddy-permitting



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...

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## eddy-resolving vs. eddy-permitting

## POM Ocean Upgrades for 2014

- Parallel implementation using MPI allows for larger domain and higher resolution
- Updated ocean physics
- 3D ocean in East Pacific
- Coupler upgraded for multiprocessor capability and advanced extrapolation/ interpolation techniques
- NetCDF I/O



Longitude

#### Version 2014 HWRF-HYCOM







- Eddy-resolving, 1/12-degree and 32layers (better res. in the mixed layer) HYCOM
- 2. IC/BC from RTOFS Global
- 3. Provide uniform ocean to E. Pac, W.Pac and Atlantic – easier to configure
- 4. Data Assimilation Global
- 5\*Data Assimilation Regional (in progress)
- 6. Re-locatable, practically anywhere in the world
- 7. ESMF compliant advantage for 3-way





MMAB/EMC 2012



#### For water temperature

- Data from buoys, drifters, and gliders. Isaac wellsampled from a combination of different field programs

- Some data is just 0m, or 1m. But have ten profile datasets down to 50-1000 m

- model values are interpolated to the exact depth where applicable. Otherwise, model's 1<sup>st</sup> layer value is used or last layer value may be used

#### For surface wind speed

- bilinear interpolation is used for both HWIND and model wind data at the observed locations

- Model wind data are 10-m winds from nested grid

#### Model runs

- Study done for 2014-version HWRF for Aug 27 00, 06, 12, 18Z runs, and Aug 28 00Z run. 06Z shown in next slides. Results are typical for all runs



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# Surface water temperature comparisons

#### Times series comparison - east side near center; HYCOM (top) versus POM (bottom, if available)



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Wind Speed (m/s)



#### Times series comparison - west side near center; HYCOM (top) versus POM (bottom, if available)



Profile temperature Comparisons

Scatterplots of 5-day forecasts

#### Scatterplot comparison - east side near center; HYCOM (top) versus POM (bottom)



#### Scatterplot comparison - west side near center; HYCOM (top) versus POM (bottom)



#### Profile comparison - drifting buoy 42516, east side of center, HYCOM (top) versus POM (bottom)



## Preliminary conclusions

- HYCOM water temperature more responsive to TC forcing than POM, especially on eastern side "cold swath" region. This is a favorable attribute.
- POM response, in contrast, is rather stiff, perhaps by design to restrict temperature drift and for operational consistency:
  - 1. POM uses diffusive mixing, which means the shear-instability driven mixing is omitted.
  - 2. POM has weak diurnal signal; initial condition based on daily GFS SST
  - 3. POM mixed layer can be too thick due to coarser vertical resolution near ocean surface
- HYCOM exhibiting positive bias. There may also be a tendency to recover from mixing processes faster than observed. This could also be an artifact of seawater potential temperature computations and peak wind stress negative bias. Track errors are also a factor in isolated incidents, but not the major issue.

Future work will include validation metrics of all five runs, mixing depth examination, and PBL physics sensitivity studies